

Code No: 156AR

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY HYDERABAD**B. Tech III Year II Semester Examinations, July - 2023****DIGITAL SIGNAL PROCESSING****(Common to ECE, EIE)****Time: 3 Hours****Max. Marks: 75****Note:** i) Question paper consists of Part A, Part B.

ii) Part A is compulsory, which carries 25 marks. In Part A, Answer all questions.

iii) In Part B, Answer any one question from each unit. Each question carries 10 marks and may have a, b as sub questions.

PART – A**(25 Marks)**

- 1.a) What are the conditions a system to be a linear? [2]
- b) How to convert continuous signal to discrete signal? [3]
- c) State Dirichlet conditions. [2]
- d) What is the relation between ZT and DFT? [3]
- e) What are the different conversion methods are used to convert analog filters to digital filters? [2]
- f) What are the advantages of Chebyshev filters? What are the different types of it? [3]
- g) What is effect of window length in the design of FIR filters? [2]
- h) Compare FIR and IIR filters. [3]
- i) What are the conditions that a system to be stable? [2]
- j) What are the three important factors are presented for choosing among the various IIR system realizations? [3]

PART – B**(50 Marks)**

- 2.a) The discrete time system $y(n) = ny(n-1) + x(n)$, $n > 0$ is at rest. Check if the system is linear time invariant and BIBO stable.
- b) Determine the impulse response $h(n)$ for the system described by the second-order difference equation $v(n) - 3v(n-1) - 4v(n-2) = x(n) + 2x(n-1)$. [5+5]

OR

- 3.a) Determine if the system having the system function:

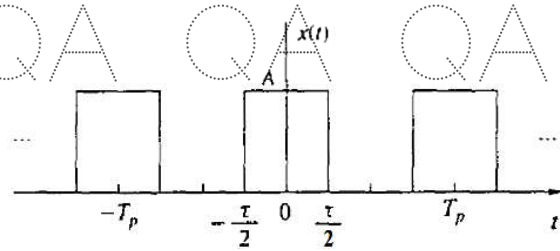
$$H(z) = \frac{1}{1 - \frac{2}{4}z^{-1} - \frac{1}{2}z^{-2}}$$

Is stable.

- b) Design an interpolator that increases the input sampling rate by a factor of $I = 5$. [5+5]



4.a) Determine the Fourier series of the rectangular pulse train signal show in Figure below:



b) Find eight point DFT for the following sequence: $x(n) = \begin{cases} 1 & n = 0 \\ 0 & 1 \leq n < 4 \\ 1 & 5 \leq n < 7 \end{cases}$ [5+5]

OR

5.a) Compute the eight point DFT of the sequence $x(n) = \begin{cases} 1, & 0 \leq n < 7 \\ 0, & \text{otherwise} \end{cases}$. By using the decimation-in-frequency FFT algorithm.

b) Draw the flow graph of the radix-2 DIT FFT algorithm for $N = 16$ and eliminate all signal paths that originate from zero inputs assuming that only $x(0)$ and $x(1)$ are nonzero. [6+4]

6.a) Determine the order and the poles of a lowpass Butterworth filter that has a -3-dB bandwidth of 500 Hz and an attenuation of 40 dB at 1000 Hz.

b) Convert the analog filter with system function:

$$H_a(s) = \frac{s + 0.1}{(s + 0.1)^2 + 16}$$

Into a digital IIR filter by means of the impulse invariance method. The digital filter is to have a resonant frequency of $\omega_r = \pi/2$. [4+6]

OR

7. Find the system function $H(z)$ of the lowest order Chebyshev digital filter that meets the following specifications:

a) 1 dB ripple in the passband $0 \leq \omega \leq 0.3\pi$

b) At least 60dB attenuation in the stopband $0.35\pi \leq \omega \leq \pi$. Use the bilinear transformation. [5+5]

8. Design an FIR linear phase, digital filter approximating the ideal frequency response

$$H_d(\omega) = \begin{cases} 1 & \text{for } |\omega| \leq \pi \\ 0 & \text{for } \frac{\pi}{2} \leq |\omega| \leq \pi \end{cases}$$

Determine and plot the magnitude and phase response of the filter using Hanning window. [10]

OR

9. Determine the coefficients $\{h(n)\}$ of a linear-phase FIR filter of length $M = 15$ which has a symmetric unit sample response and a frequency response that satisfies the condition.

[10]

$$H_r\left(\frac{2\pi k}{15}\right) = \begin{cases} 1 & k = 0, 1, 2, 3 \\ 0 & k = 4, 5, 6, 7 \end{cases}$$



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10. Given a filter $y(n) = \frac{1}{3}[x(n) + x(n-1) + x(n-2)]$. Obtain and plot the magnitude, dB magnitude, phase, frequency response for the filter. [10]

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OR
11. Consider an FIR filter with system function $H(z) = 1 + 2.88z^{-1} + 3.40z^{-2} + 1.74z^{-3} + 0.4z^{-4}$. Sketch the direct form I, parallel form realizations of the filter and determine in detail the corresponding input and output equations. Is the system minimum phase? [10]

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